Modeling of Thermo-Fluid Systems with Modelica

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Content

- Installation of Dymola
- Introduction
- Separation of Component and Medium
- Property models in Media: main concepts
- Components, control volumes and ports
- Balance equations
- Index reduction and state selection
- Numerical regularization
- Exercises

Installation

- Install Dymola and libraries from CD
- Open CD in Explorer
  - Creat work-directory in Dymola folder
  - Copy folder Tutorials to Dymola\work
  - Tutorials\Thermodynamic\ThermodynamicTutorial contains prepared exercises

Separate Medium from Component

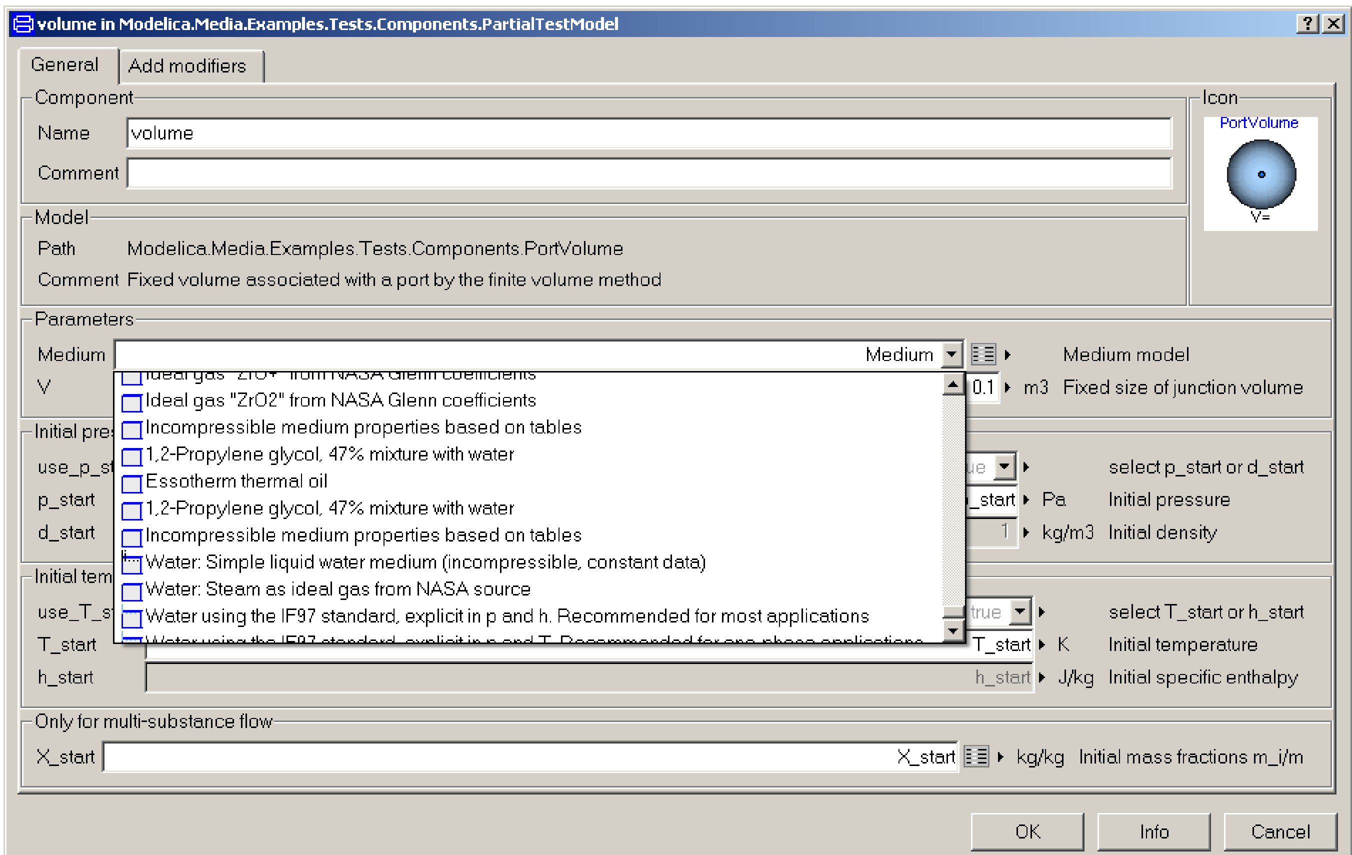
- Independent components for very different types of media (only constants or based on detailed Helmholtz function)
- Introduce "Thermodynamic State" concept: minimal and *replaceable* set of variables needed to compute all properties
- Calls to functions take a state-record as input and are therefore identical calls for e.g. Ideal gas mixtures and Water

```
redeclare record extends ThermodynamicState "thermo state variables"
      AbsolutePressure p "Absolute pressure of medium";
      Temperature T "Temperature of medium";
      MassFraction X[nS] "Mass fractions (= (comp. mass)/total mass)";
end ThermodynamicState;

redeclare record extends ThermodynamicState "thermo state variables"
      AbsolutePressure p "Absolute pressure of medium";
      SpecificEnthalpy h “specific enthalpy of medium";
end ThermodynamicState;
```

Separate Medium from Component

- Medium models are “replaceable packages” in Modelica, selected via drop-down menus in Dymola



Media Models

- Every medium model provides **3 equations** for **5 + nX variables**

Variable	Unit	Description
T	K	temperature
p	Pa	absolute pressure
d	kg/m^3	density
u	J/kg	specific internal energy
h	J/kg	specific enthalpy (h = u + p/d)
X_i[nX_i]	kg/kg	independent mass fractions m_i/m
X[nX]	kg/kg	All mass fractions m_i/m. X is defined in BaseProperties by: X = **if** reducedX **then** vector([X_i; 1-**sum**(X_i)]) **else** X_i

Two variables out of p, d, h, or u, as well as the mass fractions X_i are the **independent** variables and the medium model basically provides equations to compute the remaining variables, including the full mass fraction vector X

Separate Medium from Component, II

How should components be written that are independent of the medium (and its independent variables)?

……

```
package Medium = Modelica.Media.Interfaces.PartialMedium;
    Medium.BaseProperties medium;
  equation
  // mass balances
       der(m)  = port_a.m_flow + port_b.m_flow;
       der(mXi) = port_a_mXi_flow + port_b_mXi_flow;
             m = V*medium.d;
            mXi = M*medium.Xi; //only the independent ones, nS-1!
  // Energy balance
             U = M*medium.u;
        der(U) = port_a.H_flow+port_b.H_flow;
```

Important note: only 1 less mXi then components are integrated.
“i” stands for “independent”!

Balance Equations and Media Models are decoupled

```
// Balance equations in volume for single substance:
     m = V*d;                // mass of fluid in volume
     U = m*u;                // internal energy in volume
der(m) = port.m_flow;         // mass balance
der(U) = port.H_flow;         // energy balance

// Equations in medium (independent of balance equations)
   d = f_d(p,T);
   h = f_h(p,T);
   u = h – p/d;
```

Assume m, U are selected as states, i.e., m, U are assumed to be known:

```
   u := U/m;
   d := m/V;
   res1 := d – f_d(p,T)       }
   res2 := u + p/d – f_h(p,T) }
```

As a result, non-linear equations have to be solved for p and T:

Use preferred states

the independent variables in media models are declared as preferred states:

AbsolutePressure p(stateSelect = StateSelect.prefer)
Tool will select p as state, if this is possible

```
d := f_d(p,T);
h := f_h(p,T);
u := h – p/d;
m := V*d;
U := m*u;
```

→

```
der(U) = der(m)*u + m*der(u)
der(m) = V*der(d)
der(u) = der(h) – der(p)/d + p/d^2*der(d)
der(d) = der(f_d,p)*der(p) + der(f_d,T)*der(T)
der(h) = der(f_h,p)*der(p) + der(f_h,T)*der(T)
```

der (f_d, p) is the partial derivative of f_d w.r.t. p

- index reduction is automatically applied by tool to rewrite the equations using p, T as states (linear system in **der**(p) and **der**(T))
- no non-linear systems of equations anymore
- different independent variables are possible (tool just performs different index reductions)

Incompressible Media

Same balance equations + special medium model:

- Equation stating that density is constant (d = d_const) or that density is a function of T, (d = d(T))
- User-provided initial value for p or d is used as guess value (i.e. 1 initial equation and not 2 initial equations)

Automatic index reduction transforms differential equation for mass balance into algebraic equation:

```
     m = V*d;
der(m) = port.m_flow;
```

→

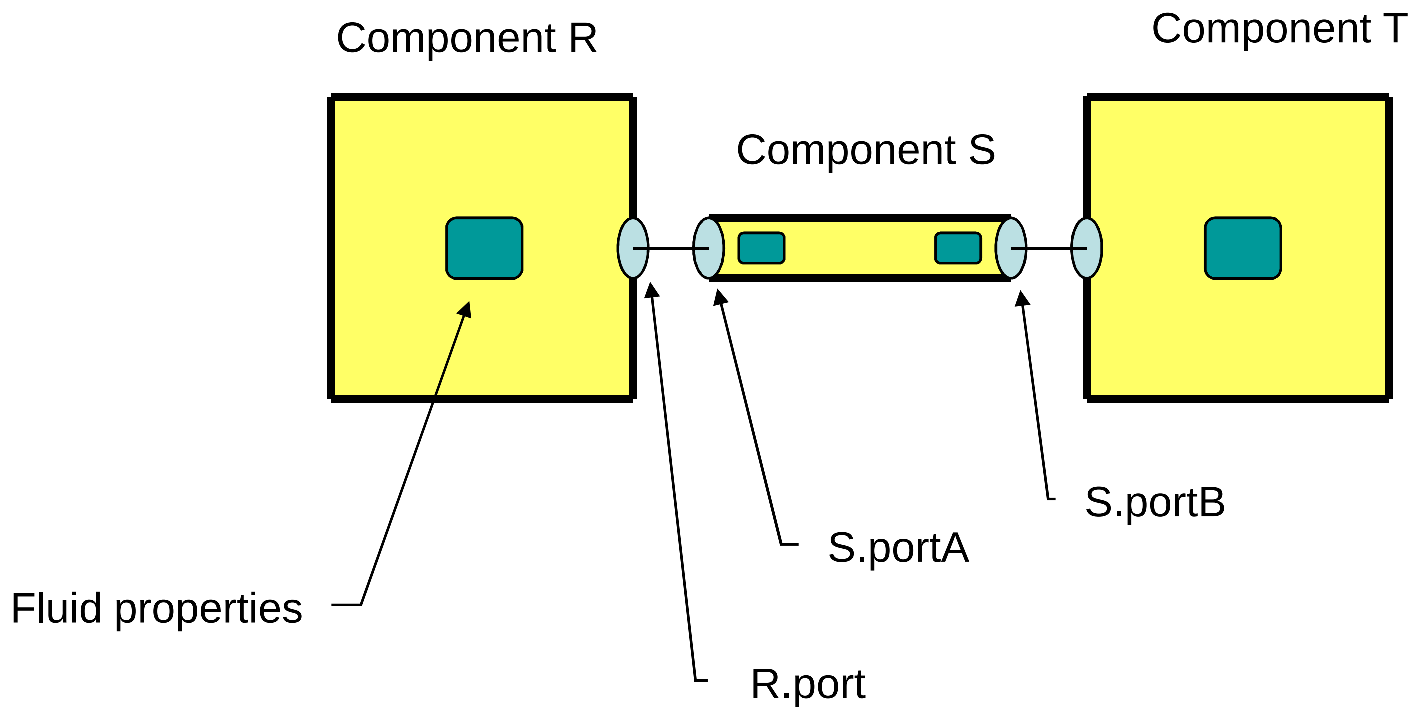
```
der(m) = V*der(d);
```

→

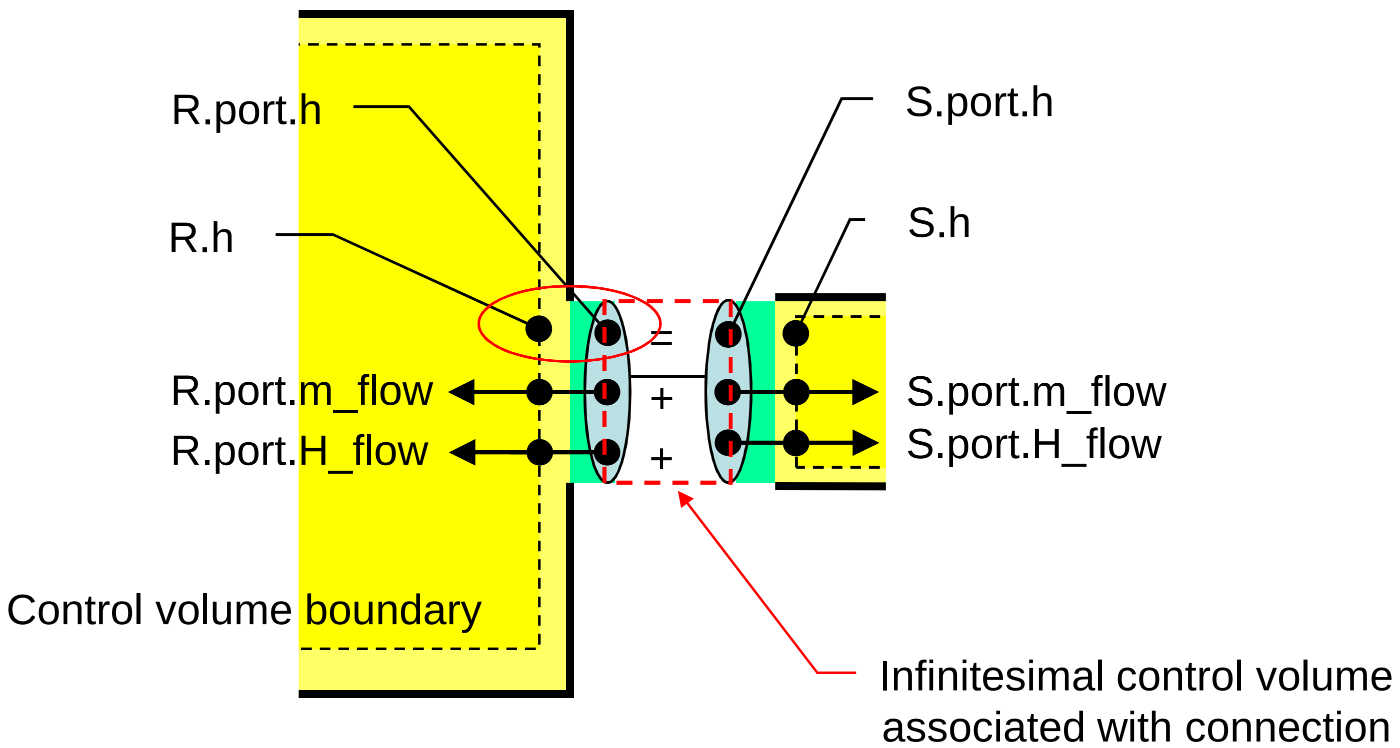
```
0 = port_a.m_flow + port_b_mflow;
```

Connectors and Reversible flow

- Compressible and non-compressible fluids
- Reversing flows
- Ideal mixing



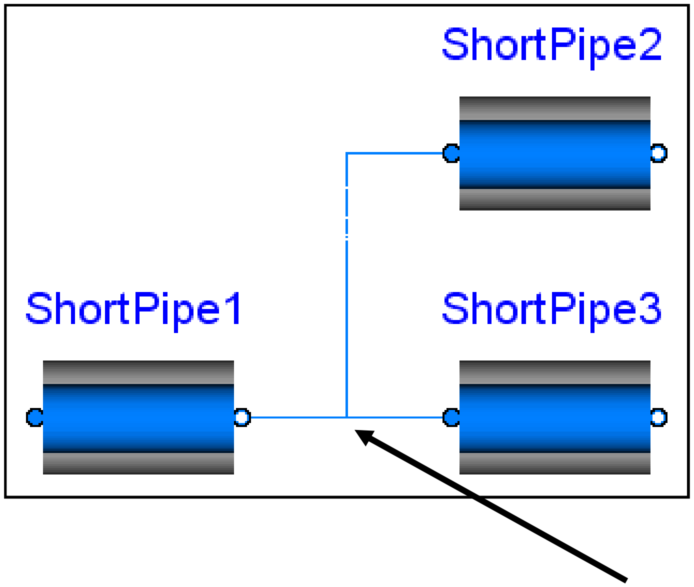
The details – boundary conditions



$$\dot{H} = \begin{cases} \dot{m} h_{port} & \dot{m} > 0 \\ \dot{m} h & otherwise \end{cases}$$

2. Modelica.Fluid Connector Definition

The interfaces (connector **FluidPort**) are defined, so that arbitrary components can be connected together



- correct for **all media** of Modelica_Media (incompressible/compressible, one/multiple substance, one/multiple phases)
- **Diffusion not included**

- Infinitesimal small volume in connection point.
- **Mass**- and **energy balance** are always **fulfilled** (= ideal mixing).
- If ideal mixing is not sufficient, a special component to define the mixing must be introduced. This is an advantage in many cases, and is thus available in Modelica.Fluid

Connector

Infinitesimal control volume associated with connection

- **flow** variables give mass- and energy-balances
- Momentum balance not considered – forces on junction gives balance

Medium in connector allows to check that only valid connections can be made!

Reminder: flow variables sum to 0 at connection point

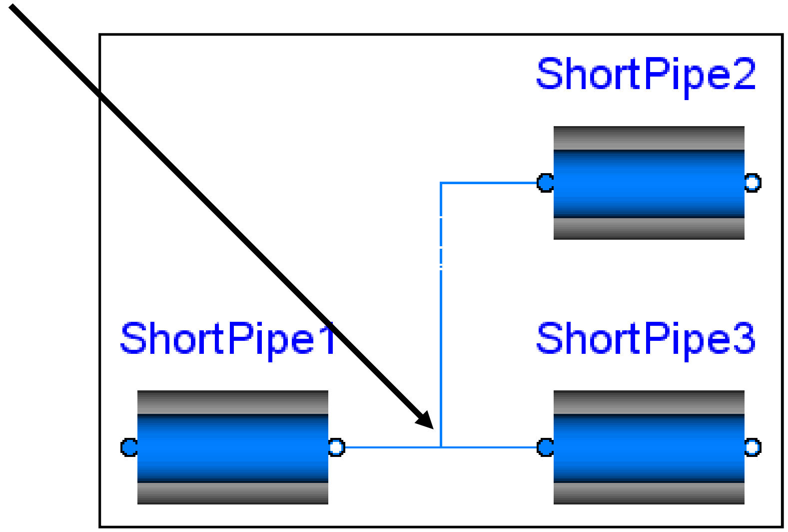
```
connector FluidPort
 replaceable package Medium =
 Modelica_Media.Interfaces.PartialMedium;

 Medium.AbsolutePressure  p;
 flow Medium.MassFlowRate m_flow;

 Medium.SpecificEnthalpy     h;
 flow Medium.EnthalpyFlowRate H_flow;

 Medium.MassFraction      Xi     [Medium.nXi]
 flow Medium.MassFlowRate mXi_flow[Medium.nXi]
end FluidPort;
```

Balance equations for infinitesimale balance volume without mass/energy/momentum storage:



Intensive variables (since ideal mixing):

p1=p2=p3; h1=h2=h3; ....

Mass balance:

0 = m_flow1 + m_flow2 + m_flow3

Energy balance:

0 = H_flow1 + H_flow2 + H_flow3

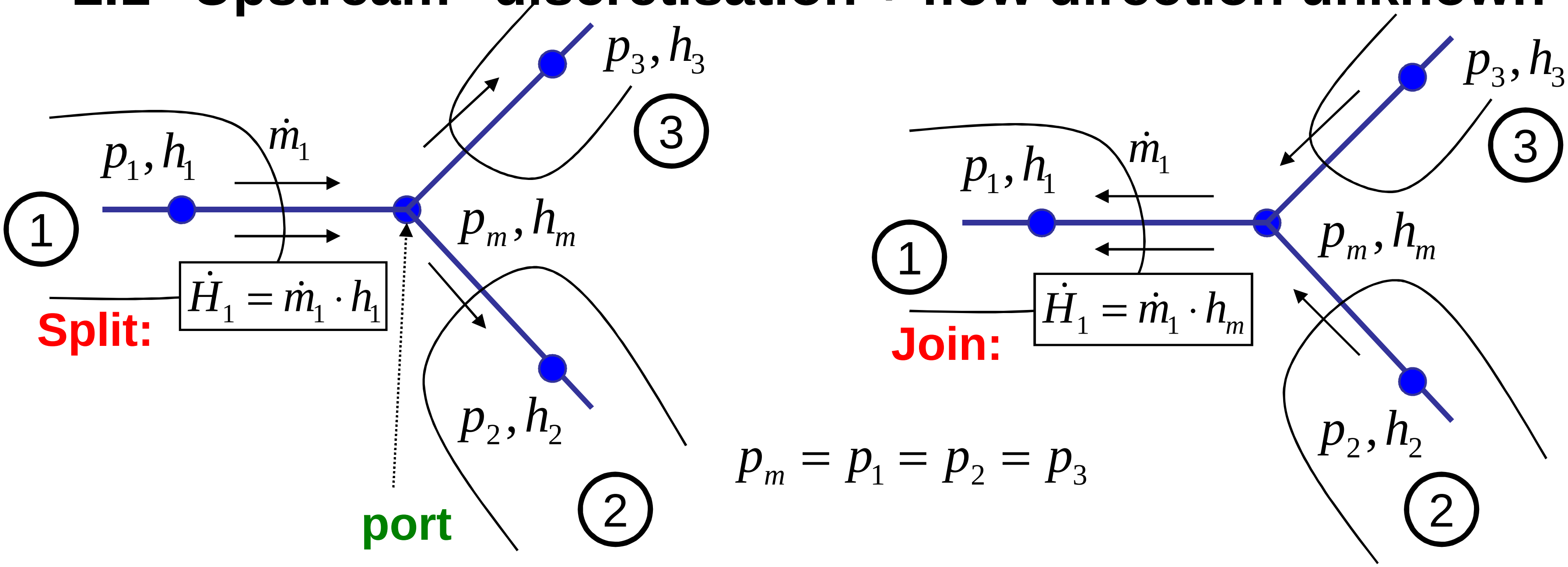
{Momentum balance (v=v1=v2=v3; i.e., velocity vectors are parallel)

0 = m_flow1*v1 + m_flow2*v2 + m_flow3*v3
= v*(m_flow1 + m_flow2 + m_flow3)}

Conclusion:

Connectors must have "**m_flow**" and "**H_flow**" and define them as "**flow**" variable since the default connection equations generate the mass/energy/momentum balance!

2.1 "Upstream" discretisation + flow direction unknown



$$p_m = p_1 = p_2 = p_3$$

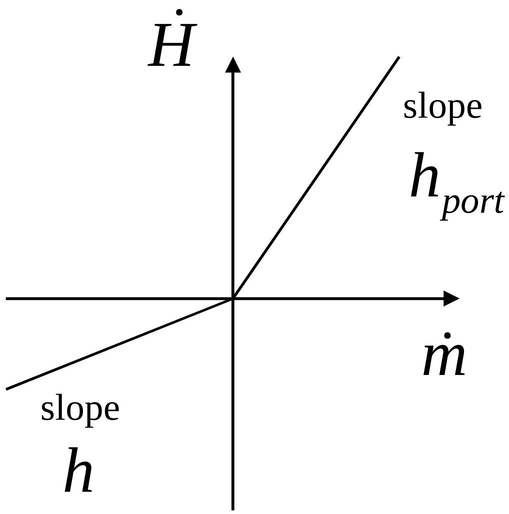
Variables in connector
port of component 1:

$$p_m, h_m, \dot{m}_1, \dot{H}_1$$

```
connector FluidPort
  SI.Pressure                  p; //pm
  SI.SpecificEnthalpy          h; //hm
  flow SI.MassFlowRate         m_flow;
  flow SI.EnthalpyFlowRate H_flow;
end FluidPort;
```

Energy flow rate and port specific enthalpy

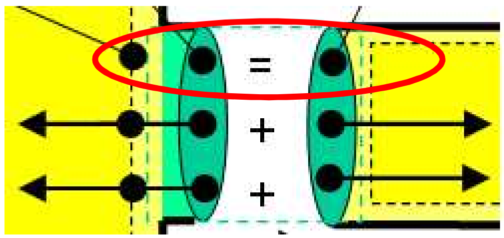
$$\dot{H} = \begin{cases} \dot{m} h_{port} & \dot{m} > 0 \\ \dot{m} h & otherwise \end{cases}$$




```
H_flow=semiLinear(m_flow, h_port, h)
```

Solving semiLinear equations

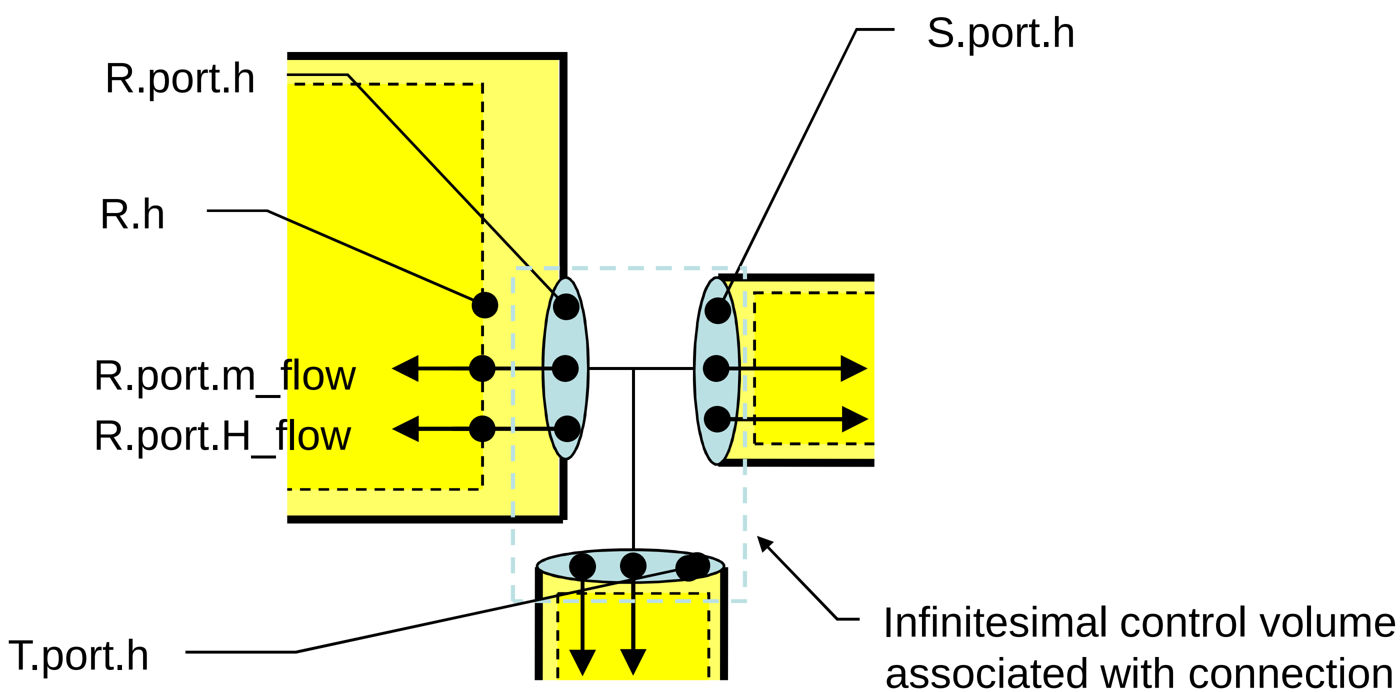
Component R Component S




```
R.H_flow=semiLinear(R.m_flow, R.h_port, R.h)
S.H_flow=semiLinear(S.m_flow, S.h_port, S.h)
// Connection equations
R.h_port = S.h_port
R.m_flow + S.m_flow = 0
R.H_flow + S.H_flow = 0
```

$$h_{port} = \begin{cases} h_S & \dot{m}_R > 0 \\ h_R & \dot{m}_S < 0 \\ undefined & \dot{m}_R = 0 \end{cases}$$

Three connected components



- Use of semiLinear() results in systems of equations with many if-statements.
- In many situations, these equations can be solved symbolically

Splitting flow

- For a *splitting* flow
  from R to S and T
  (R.port.m_flow < 0, S.port.m_flow > 0 and T.port.m_flow > 0)

- h = -R.port.m_flow*R.h /
  (S.port.m_flow + T.port.m_flow)

- h = R.h

Mixing flow

- For a *mixing* flow
  from R and T into S
  (R.port.m_flow < 0, S.port.m_flow < 0 and T.port.m_flow > 0)

  h = -(R.port.m_flow*R.h + S.port.m_flow*S.h) /
  T.port.m_flow
- or

  h = (R.port.m_flow*R.h+S.port.m_flow*S.h) /
  (R.port.m_flow + S.port.m_flow)

- Perfect mixing condition

Mass- momentum- and energy-balances

$$\frac{\partial(\rho A)}{\partial t}+\frac{\partial(\rho A v)}{\partial x}=0$$

$$\frac{\partial(\rho v A)}{\partial t}+\frac{\partial(\rho v^2 A)}{\partial x}=-A\frac{\partial p}{\partial x}-F_F-A\rho g\frac{\partial z}{\partial x}$$

$$\frac{\partial(\rho(u+\frac{v^2}{2})A)}{\partial t}+\frac{\partial(\rho v(u+\frac{p}{\rho}+\frac{v^2}{2})A)}{\partial x}=-A\rho v g\frac{\partial z}{\partial x}+\frac{\partial}{\partial x}(kA\frac{\partial T}{\partial x})$$

$$F_F=\frac{1}{2}\rho v\left|v\right| fS$$

Often more efficient to use certain simplifications

Finite volume method

- Integrate equations over small segment
- Introduce appropriate mean values

$$\int_a^b \frac{\partial(\rho A)}{\partial t} dx + \rho A v\Big|_{x=b} - \rho A v\Big|_{x=a} = 0$$

$$\frac{dm}{dt} = \dot{m}_a + \dot{m}_b$$

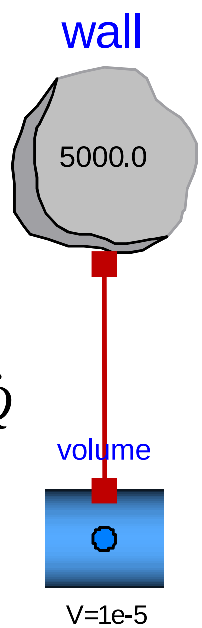
$$m = \rho_m A_m L$$

Index reduction and state selection

- Component oriented modeling needs to have maximum number of differential equations in components
- Constraints are introduced through connections or simplifying assumptions (e.g. density=constant)
- Tool needs to figure out how many states are independent
- Not usually used in fluid or thermodynamic modeling
- Very useful also in thermo-fluid systems
  - Unify models for compressible/incompressible fluids
  - High efficiency of models independent from input variables of property computation
- Beware: overusing it may baffle you!

Index reduction and state selection

- Example: connect an incompressible medium to a metal body under the assumption of infinite heat conduction (Exercise 3-1).
- Realistic real-world example: model of slow dynamics in risers and drum in a drum boiler (justified simplification used in practice)



unknown heat flow $\dot{Q}$

Dynamic equations: energy balances for wall and fluid

$$m\,cp\,\frac{dT_{wall}}{dt} = \dot{Q}$$

$$\frac{dU}{dt} = \sum \dot{H} - \dot{Q}$$

constraint equation

$$T_{wall} = T_{fluid}$$

→ unknown heat flow keeps temperatures equal

Index reduction and state selection

Differentiate the constraint equation:

$$\frac{dT_{wall}}{dt} = \frac{dT_{fluid}}{dt}$$

$$U = u\, m$$

Definition of u for simple Incompressible fluid

$$h(T, p) = h(T) + \frac{p - p_0}{\rho}$$

$$u(T) = h(T) - \frac{p_0}{\rho}$$

Expand fluid definition

$$\frac{dh(T)}{dT}\frac{dT_{fluid}}{dt} - \frac{p_0}{\rho} = cp(T)\frac{dT_{fluid}}{dt} - \frac{p_0}{\rho}$$

Re-write energy balance with T as state

$$\frac{dU}{dt} = m\left(cp(T)\frac{dT_{fluid}}{dt} - \frac{p_0}{\rho} \right)$$

Index reduction and state selection

Using $$\frac{dT_{wall}}{dt} = \frac{dT_{fluid}}{dt}$$

Some rearranging yields:

$$\left(m_{wall} cp_{wall} + m_{fluid} cp_{fluid}\right) \frac{dT}{dt} = \sum \dot{H} + \frac{p_0}{\rho}$$

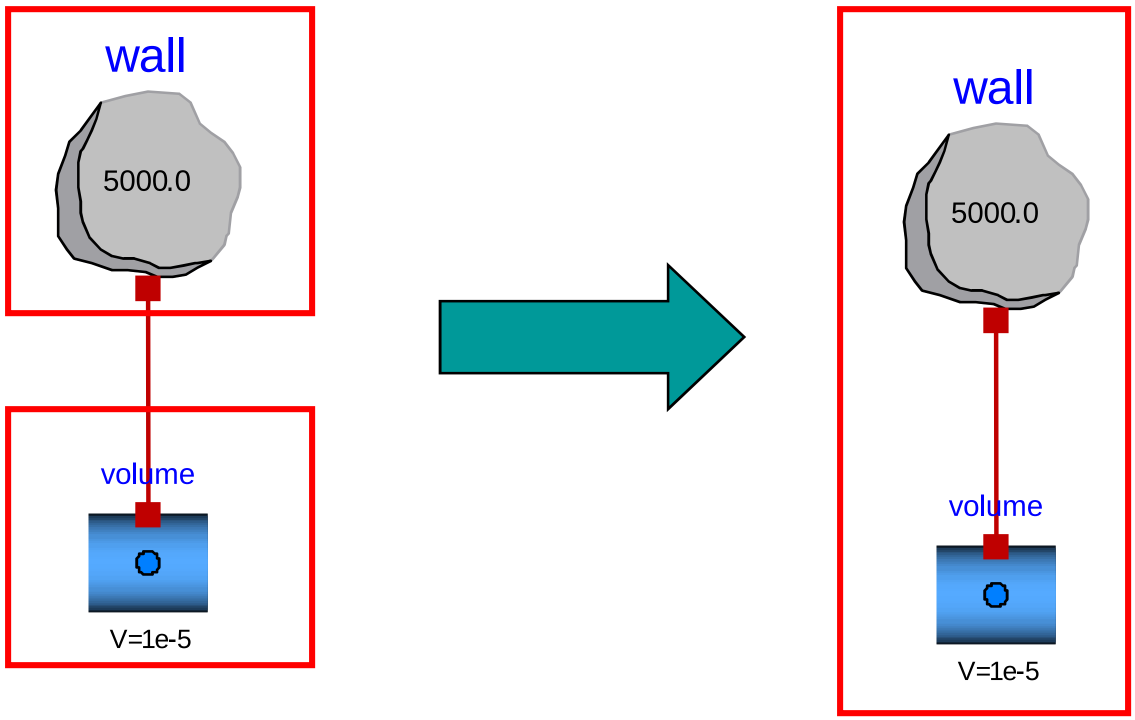
→ Combined energy balance for metal and fluid

$$\dot{Q} = \sum \dot{H} - m_{fluid} cp_{fluid} \frac{dT}{dt} - \frac{p_0}{\rho}$$

Unknown flow Q computed from temperature derivative

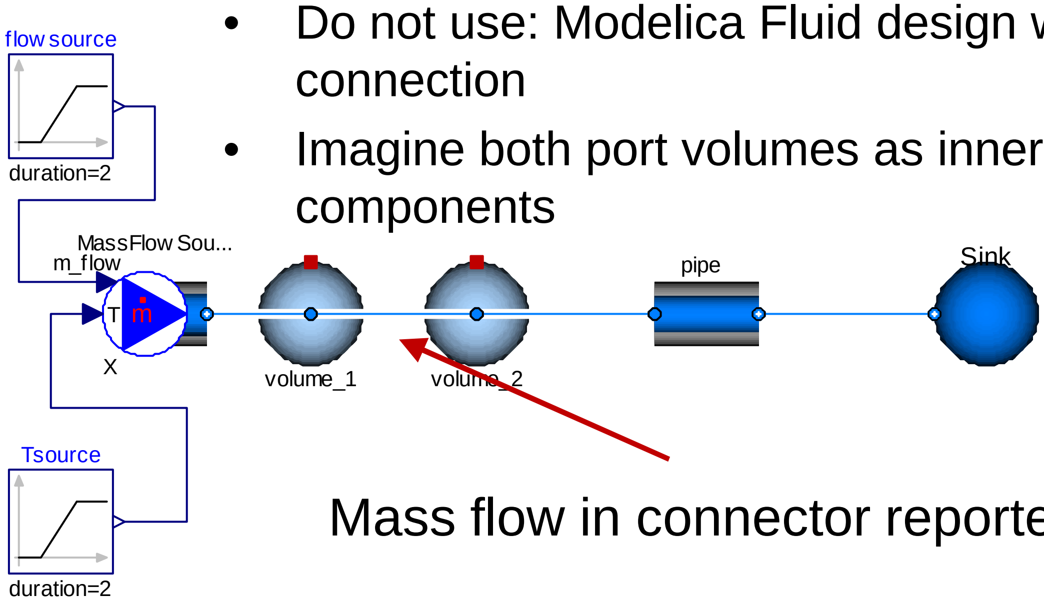
Index reduction and state selection

- Because temperatures are forced to be equal, we get to one lumped energy balance for volume and wall instead of 2
- Side effect: the independent state variable is now T, not U any more
- Heavily used in Modelica.Media and Fluid to get efficient dynamic models



Index reduction: not always intuitive

- Index reduction between 2 lumped volumes without the semiLinear() operator: for single substance, 4 states, e.g. p and T in each volume, reduce to 2 states.
- Much better to use 1 volume model (but maybe hard to notice in hierarchical models).
- Results are difficult to interpret: mass flow between volume is reported as 0 because it is transformed into a slack variable
- Do not use: Modelica Fluid design will try to prohibit this type of connection
- Imagine both port volumes as inner parts of hierarchical components



Mass flow in connector reported as 0

Index reduction and state selection

- Many other situations:
  – 2 volumes are connected
  – Tanks have equal pressure at bottom
  – Change of independent variables, though not originally a high index problem, uses the same mechanism (see also slide 11)
- Big advantage in most cases:
  – Independence of fluid and component or plant model
  – Highly efficient
  – More versatile models
- Potential drawbacks
  – All functions have to be symbolically differentiable
  – Complex manipulations
  – If manipulations not right, model can have unnecessary non-linear equations – potentially slow simulation
  – See exercises

Regularizing Numerical Expressions

- Robustness: reliable solutions wanted
  in the complete operating range!
- Difference between static and dynamic models
  - Dynamic models are used in much wider operating range
- Empirical correlations not adapted to robust numerical solutions (only locally valid, singular and non-physical at other points)
- Non-linear equation systems or functions
- Singularities
- Handling of discontinuities

Singularities

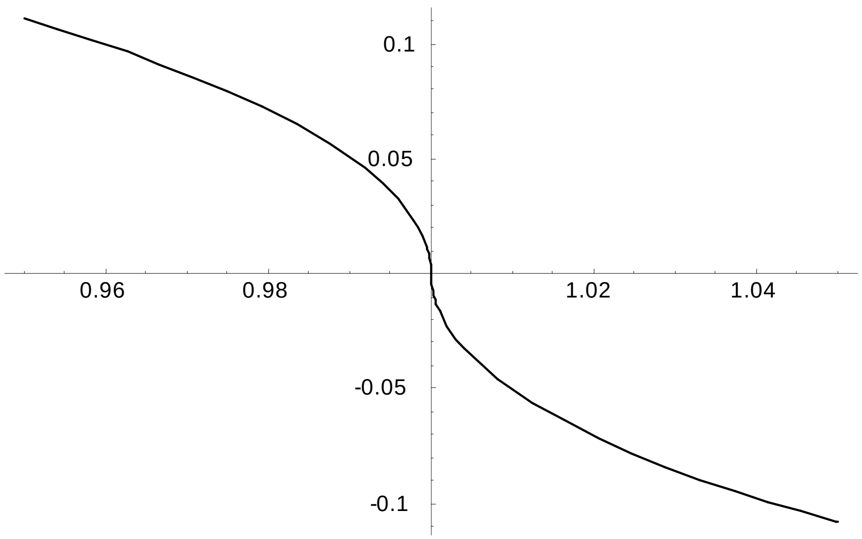
- *functions with singular points or singular derivatives shall be regularized.*

  - Empirical functions are often used outside their region of validity to simplify models.
  - Most common problem: infinite derivative, causing *inflection*.

Root function Example

- Textbook form of turbulent flow resistance

$$\dot{m} - k\, sign\left(\Delta p\right)\sqrt{\rho\, abs(\Delta p)} = 0$$



→ Infinite derivative at origin

Singularities

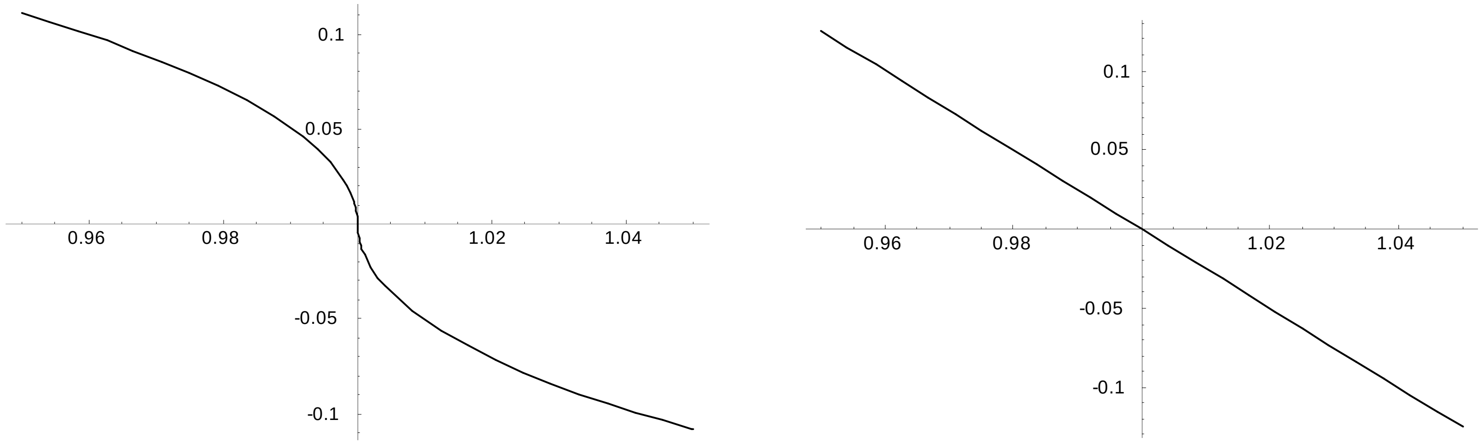
- Infinite derivative causes trouble with Newton-Raphson type solvers:
  Solutions are obtained from following iteration:

$$z^{j+1} = z^j + \frac{f(z^j)}{\dfrac{\partial f(z^j)}{\partial z^j}} \approx \Delta z^j + \frac{f(z^j)}{\dfrac{\Delta f(z^j)}{\Delta z^j}}$$

For $\dfrac{\partial f(z^j)}{\partial z^j} \rightarrow \infty$, the step size goes to 0.

This is called *inflection problem*

Root function remedy



- Replace singular part with local, non-singular substitute
  - result should be qualitatively correct
  - the overall function should be C^1 continuous
  - No singular derivatives should remain!

Log-mean Temperature

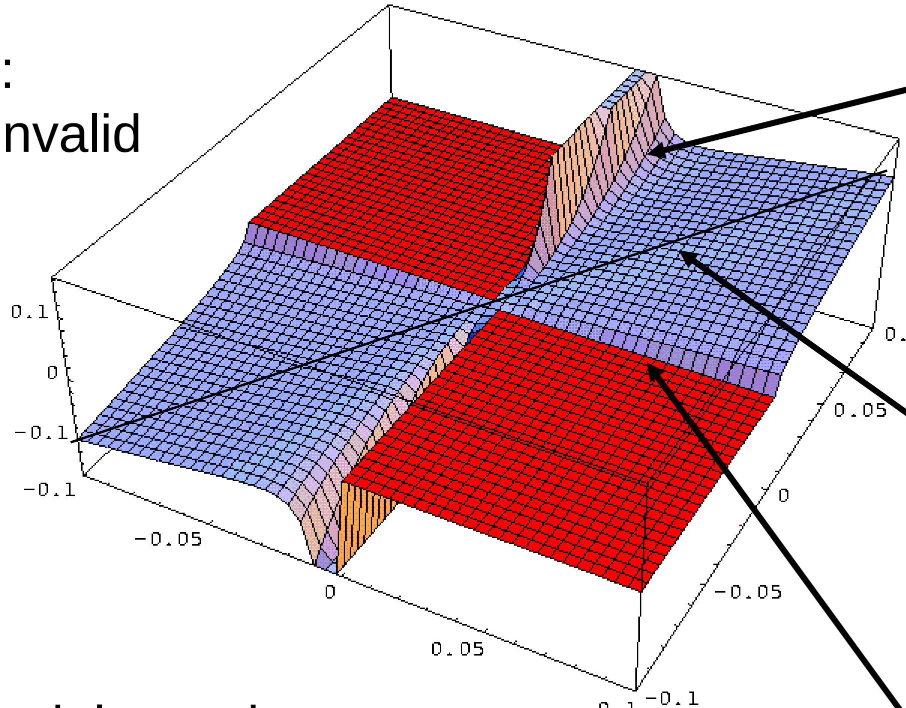
Log-mean Temperature $$\Delta T_{lm} = \frac{\Delta T_1 - \Delta T_2}{\ln(\Delta T_1 / \Delta T_2)}$$

- Invalid for all $\mathrm{sign}(\Delta T_1) \times \mathrm{sign}(\Delta T_2) < 0$
- numerical singularities for

$$\Delta T_1 = \Delta T_2,\ \Delta T_1 \to 0,\ \Delta T_2 \to 0$$

Log-mean Temperature Difference

Red areas:
log-mean invalid



Boundaries with ridges

$\Delta T1 = \Delta T2$ singularity

Boundaries with infinite derivative

Dynamic models can be in any quadrant!

Summary

Framework for object-oriented fluid modeling

- Media and component models decoupled
- Reversing flows
- Ideal models for mixing and separation
- Index reduction for
  - transformations of media equations
  - handling of incompressible media
  - Index reduction for combining volumes
- Some issues in numerical regularization

Exercises

1. Build up small model and run with different media
   – Look at state selection
   – Check non-linear equation systems
   – Test different options for incompressible media
2. Reversing flow and singularity treatment
   – Build up model with potential backflow
   – Test with regularized and Text-book version of pressure drop
3. Index reduction and efficient state selection with fluid models, 3 different examples
   1. Index reduction through temperature constraint of solid body and fluid volume (used in power plant modeling)
   2. Index reduction between 2 well mixed volumes
   3. Index reduction between tanks without a pressure drop in between.
4. Non-linear equation systems in networks of simple pressure losses
5. Reversing and 0-flow with liquid valve models

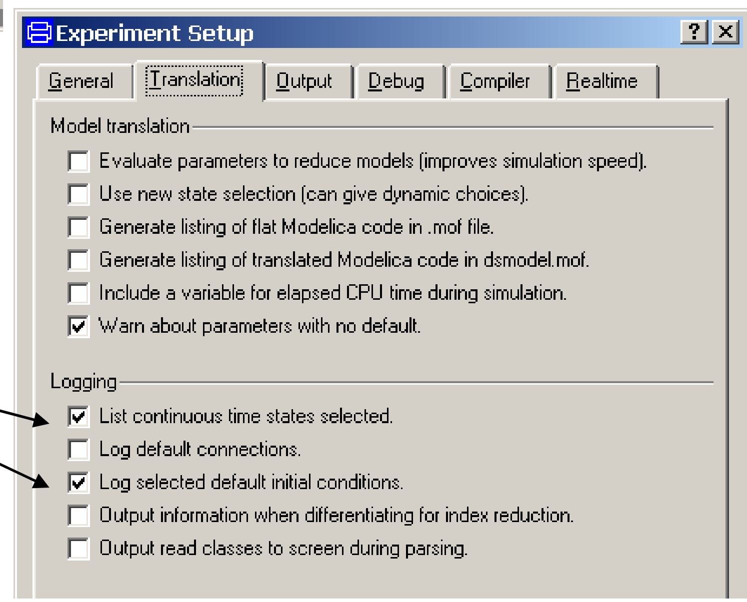
Exercises

- All exercises are explained step by step in the info-layer in Dymola of the corresponding exercise models.
- All models are prepared and can be run directly, the the exercises modify and explore the models

1

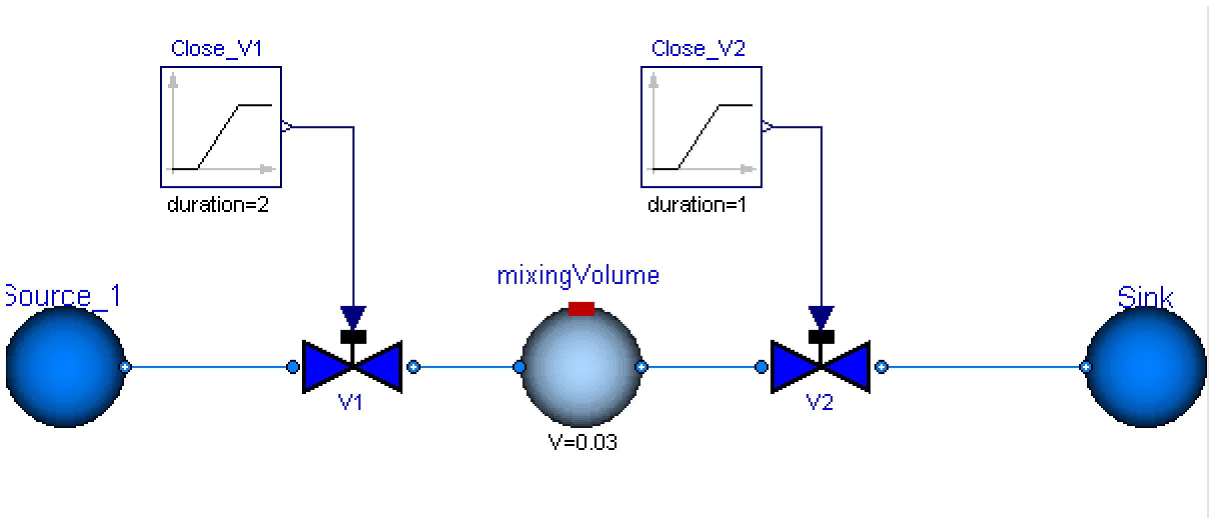
- In simulation setup dialog the settings to the left can be helpful to follow the symbolic manipulation process.

2



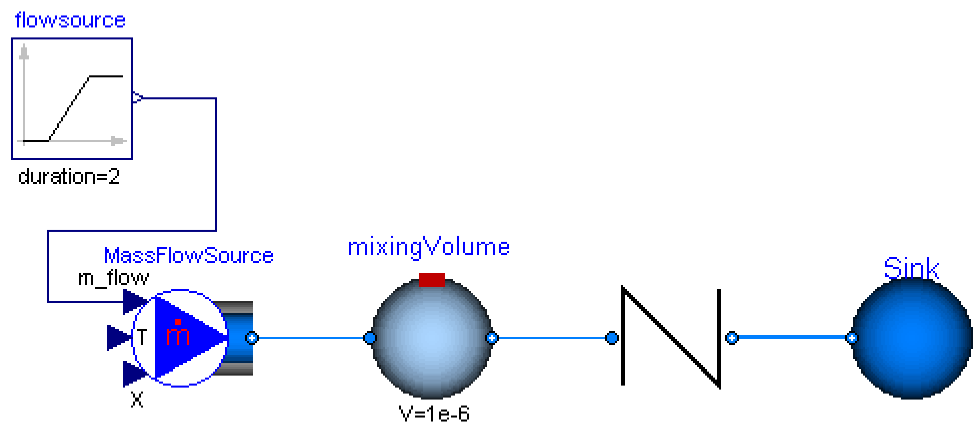
Exercise 1

- Using different Media with the same plant and test of 0-flow conditions



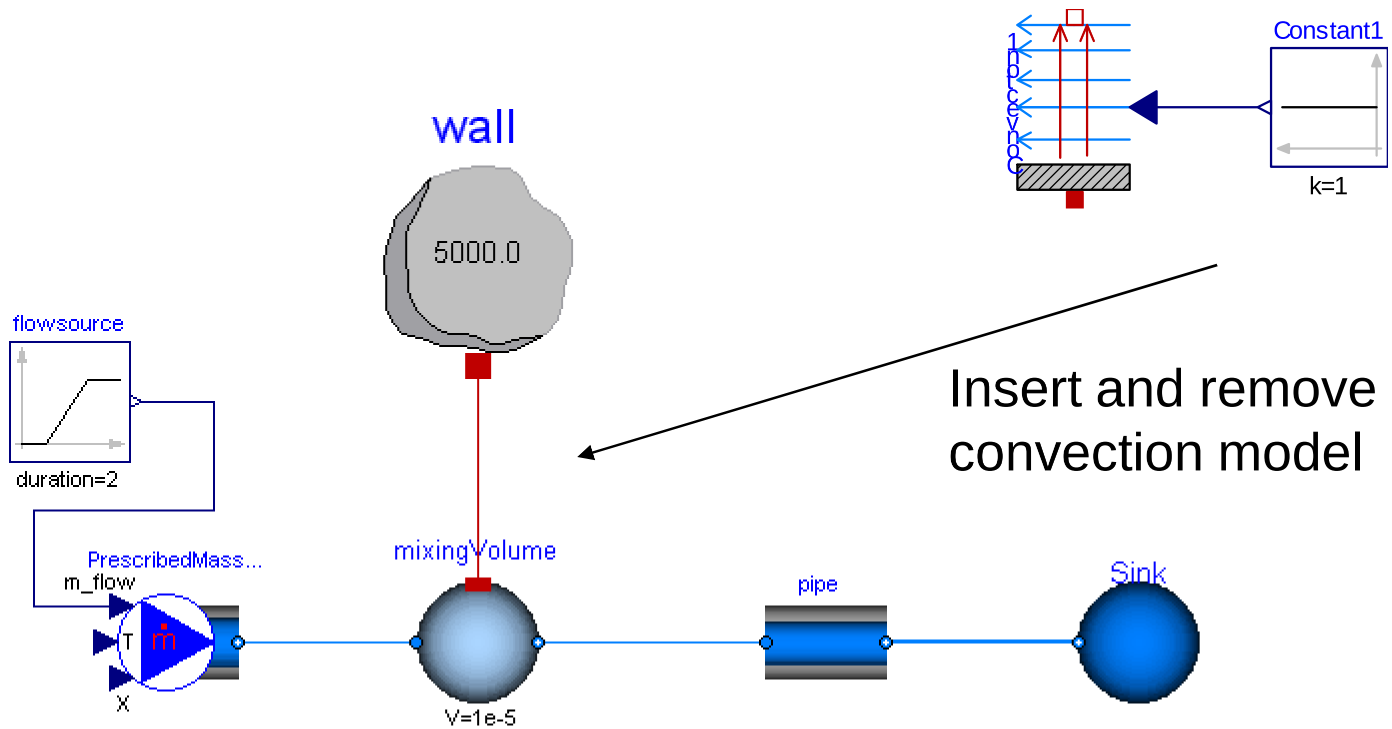
Exercise 2

- Effect of Square root singularity



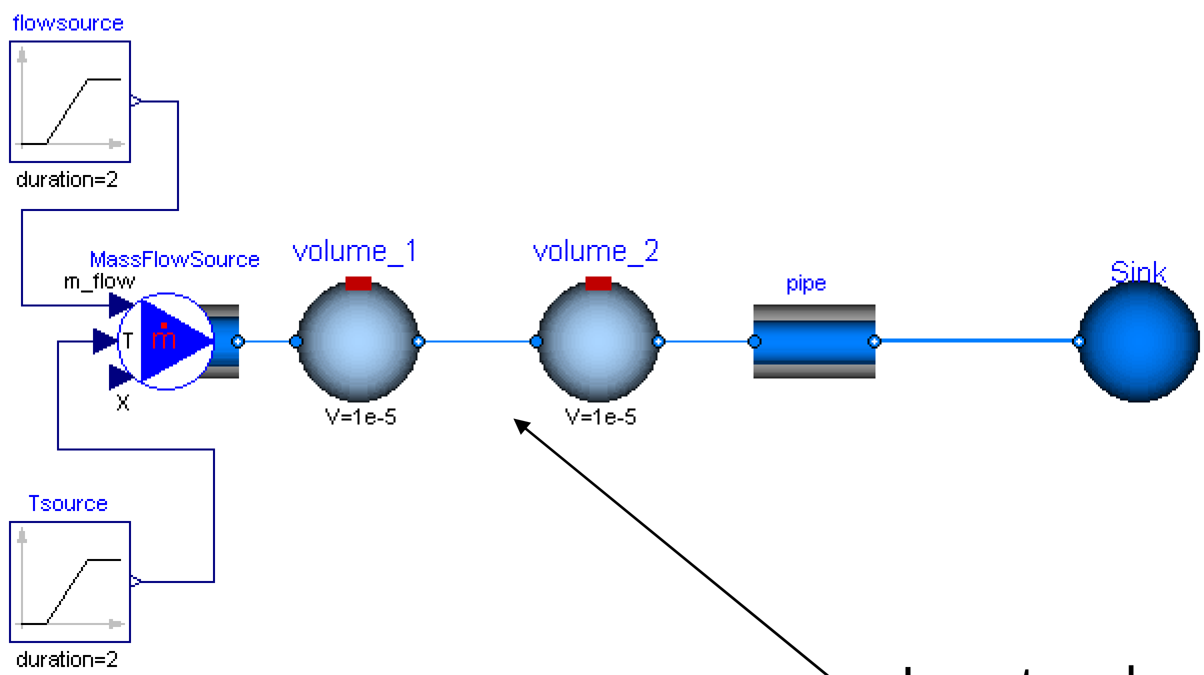
Exercise 3-1

- Index reduction between solid body and fluid volume



Exercise 3-2

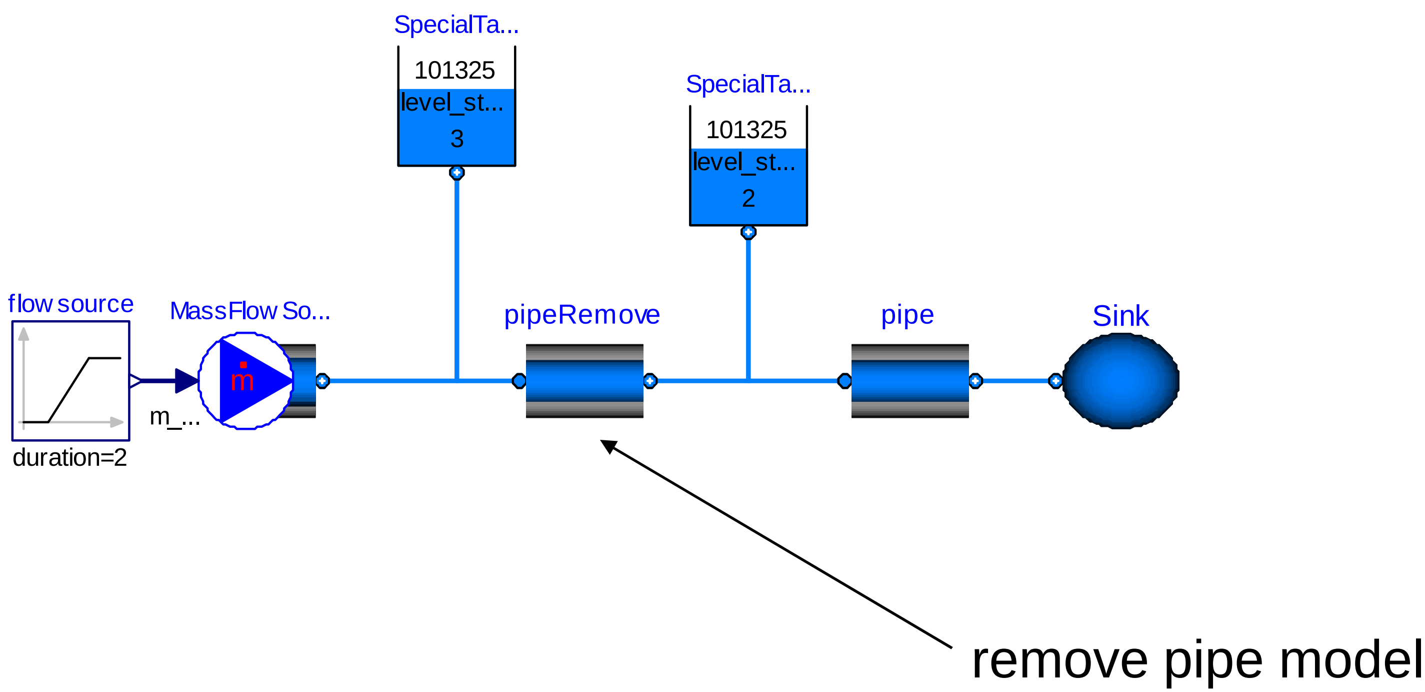
- Index reduction between 2 well mixed fluid volumes



Insert and remove pipe model

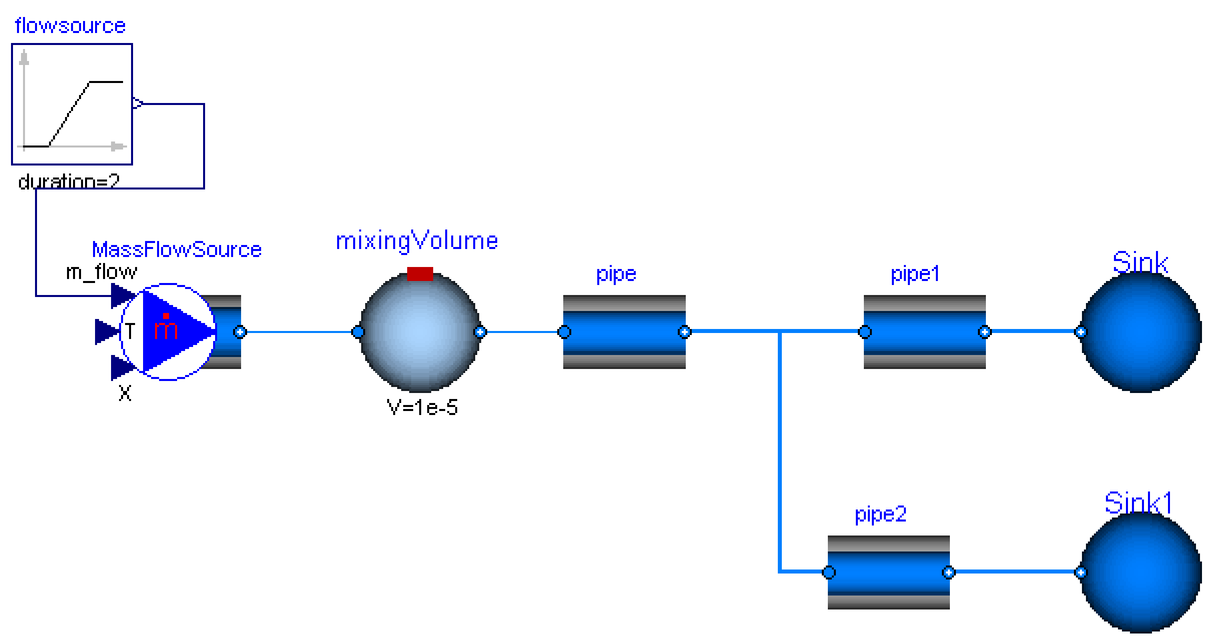
Exercise 3-3

- Index reduction of one state only between 2 tank models



Exercise 4

- Non-linear equations in pipe network models



Exercise 5

- Reversing flow for a liquid valve